Multiple satellites observation evidence: High- m Poloidal ULF waves with time-varying polarization states

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Abstract: We report multi-spacecraft observations of ULF waves from Van Allen Probes (RBSP), Magnetospheric Multiscale (MMS), Time History of Events and Macroscale Interactions during Substorm (THEMIS), and Geostationary Operational Environmental Satellites (GOES). On August 31, 2015, global-scale poloidal waves were observed in data from RBSP-B, GOES and THEMIS from $L=4$ to $L=8$ over a wide range of magnetic local time (MLT). The polarization states varied towards purely poloidal polarity. In two consecutive orbits over 18 hours, RBSP-A and RBSP-B recorded gradual variation of the polarization states of the poloidal waves; the ratio ($|B_a|/|B_t|$) decreased from 0.82 to 0.13. After the variation of polarization states, the poloidal ULF waves became very purely poloidal waves, localized in both L and MLT. We identify the poloidal wave as second harmonic mode with a large azimuthal wave number (m) of ~ 232 . From RBSP particle measurements we find evidence that the high- m poloidal waves during the polarization variations were powered by inward radial gradients and bump-on-tail ion distributions through the $N=1$ drift-bounce resonance. Most of the time, the dominant free energy source was inward radial gradients, compared with the positive gradient in the energy distribution of the bump-on-tail ion distributions.

Keywords: poloidal waves; polarization rotation; bump-on-tail; inward gradient

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1. Introduction

The ultra-low-frequency (ULF) waves are geomagnetic field line oscillations in the frequency range 1 mHz to 1 Hz. Two main categories of ULF waves are poloidal waves and toroidal waves, with wave magnetic field oscillations in the radial and azimuthal directions, respectively.

Poloidal ULF waves can be generated from sources internal or external to the magnetosphere. External sources in the solar wind include the Kelvin-Helmholtz (K-H) instability (Southwood, 1974; Chen L and Hasegawa, 1974; Liu W et al., 2011), dynamic pressure variations (Kessel, 2008; Zong QG et al., 2007, 2009; Zhou XZ et al., 2015), and fluctuations in the foreshock region (Russell et al., 1983; Takahashi et al., 2015). Poloidal ULF waves generated by external sources usually have a low or high azimuthal wave number m and are coupled with strong compressional components (Hughes, 1994; Zong QG et al., 2009, 2017). In general, the wave number m is considered low when $m \sim 1$, intermediate when $m \sim 10$, and large when m is several tens to a few hundreds. Internal sources of poloidal ULF waves include drift-mirror instability (Cheng CZ and Lin CS, 1987), drift resonance and drift-bounce resonance (Southwood, 1976). Poloidal waves generated by internal sources generally have high- m numbers. In high beta plasmas, the

compressional component is coupled to poloidal waves in drift-mirror instabilities (Chen L and Hasegawa, 1991). In low beta plasmas, the compressional component vanishes in high- m poloidal waves (Hughes, 1994). RBSP statistical survey shows that compressional Pc 4 poloidal waves are related to solar wind dynamic pressure and that non-compressional Pc 4 poloidal waves are related to decay of the ring current (Dai L et al., 2015).

In the large m limit, the purely poloidal wave is a guided wave (Cumplings et al., 1969). Guided poloidal waves are usually generated by drift and drift-bounce resonance instabilities of ring current ions (Southwood, 1976; Engebretson et al., 1992; Oimatsu et al., 2018). Drift resonance and drift-bounce resonance instabilities are responsible for driving odd-number and even-number harmonics of poloidal waves, respectively (Southwood and Kivelson, 1982; Takahashi et al., 2011). Recent RBSP observations provide direct evidence that the fundamental mode poloidal waves are excited by drift resonance with free energy from the gradient in the particle phase space density (Dai L et al., 2013). Such fundamental mode poloidal ULF waves are linked with giant pulsations observed on the ground (Takahashi et al., 2011, 2018a). Previous studies show that second harmonic mode poloidal waves driven by drift-bounce resonance are frequently observed (Hughes et al., 1978; Singer et al., 1982; Takahashi et al., 1990, 2018b). The free energy source for the drift-bounce resonance can be bump-on-tail plasma distributions (Hughes et al., 1978; Liu W et al., 2013) and inward radial gradient of the particle phase space density (Min K et al., 2017).

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High- m poloidal waves are frequently observed (e.g., Le et al., 2011; Yeoman et al., 2000). The spatial distribution of high- m poloidal waves is usually localized. Cramm et al. (2000) recorded an event radially localized at about $L=5$ with azimuthal mode number $m=150$. Chi and Le (2015) observed a localized poloidal wave with m number of order 100 and steady wave frequency across local times and L shells. Schäfer et al. (2007) detected radial poloidal ULF oscillations by Cluster with $m\sim 30$. The morphology of the high- m poloidal mode, however, can be complicated. Recently, multiple spacecraft observations have been reported of storm time high- m ($m\sim 100$) poloidal waves of global scale (Le et al., 2017); these high- m mode waves covered a wide range of L (from 4 to 12) as well as of local times.

Toroidal ULF waves correspond to a response of the magnetosphere to large-scale disturbances (Southwood, 1974; Chen and Hasegawa, 1974). Toroidal waves are usually characterized by multiple harmonic bands in the dynamic frequency spectra (Engelbreton et al., 1986). Takahashi et al. (2015) presents a case of a multi-harmonic toroidal wave visible up to the eleventh harmonic. Eigen-frequencies of global-scale toroidal waves have been used to infer plasma mass density of the magnetosphere (Denton and Gallagher, 2000; Menk et al., 1999; Takahashi et al., 2015). In the MHD theory, toroidal waves can be transformed from purely poloidal waves through polarization state variations in nonuniform plasmas (Radoski, 1974). MHD simulations have shown that poloidal waves in the magnetosphere tend to have a finite lifetime and change to toroidal waves (Mann and Wright, 1995). Observational evidence shows that the time for polarization states to vary to toroidal waves is similar to the decay time of the poloidal wave (Sarris et al., 2009). Pc 3 ULF waves due to hot flow anomalies have been observed to exhibit polarization state variations from poloidal mode to toroidal mode (Zhao et al., 2017).

Observations of wave polarization may thus yield important information regarding the generation of ULF waves. In this study, we report time-varying polarization states from global poloidal waves to localized and purely poloidal ULF waves. We combine observations from multiple satellites, including Van Allen Probes (RBSP), Magnetospheric Multiscale (MMS), Time History of Events and Macroscale Interactions during Substorm (THEMIS), and Geostationary Operational Environmental Satellites (GOES). The organization of the paper is as follows. In Section 2.1, we show the solar wind and geomagnetic conditions for the event. In Section 2.2, we present observations of the spatial distribution of the waves and the time-varying polarization states from mixed mode to purely poloidal mode. In Section 2.3, we analyze the wave properties during the variation of polarization states. In Section 2.4, we present evidence of the sources of free energy for the second harmonic mode poloidal wave. Section 3 is summary and discussions.

2. Observations

2.1 The Solar Wind and Geomagnetic Activity Context

Figure 1 presents the solar wind and geomagnetic activity context for our event. The SYM- H index, AE index, and solar wind conditions from August 25 to September 3 are shown. The main

phase of a moderate magnetic storm started on August 26, 2015, as indicated in Figure 1a. The SYM- H decreased to the minimum value -90 nT late on August 27. The storm's main phase lasted for about 2 days, from August 26 to August 28. The recovery phase developed for about 4 days, from August 28 to September 01. During the storm's main phase and its early recovery phase, strong and continuous AE activities are seen (Figure 1b). Figures 1c–1e present solar wind proton number density (N_p), velocity (V_p), and dynamic pressure (P_{dyn}). Strong variations of P_{dyn} are seen in the main phase. In the recovery phase, both AE and P_{dyn} are small. The observed ULF waves occur in the late recovery phase and quiet time. The two vertical dashed lines indicate the interval when ULF waves are observed with time-varying polarization states from 23:00 UT on August 31 to 17:00 UT on September 1. The time-varying polarization states lasted for two RBSP orbit (18 hours) in a quiet time, during which no significant variations are seen in the solar wind or geomagnetic activities.

2.2 Spatial Distribution of ULF Waves and Polarization Variation

Figure 2 is an overview of the spatial distribution of observed ULF waves. Figure 2a shows the observation of initially poloidal ULF waves, by RBSP-B, GOES-13 and THEMIS-A, in the xy -plane of GSM coordinate near the day 2015-08-31. Locations of observed ULF wave activity are marked with colors. The red corresponds to the observation of waves by RBSP-B from 23:00 UT on August 31 to 02:30 UT on September 1. The pink corresponds to the ULF waves observed by GOES-13 from 23:20 UT on August 31 to 02:00 UT on September 1. The green corresponds to the waves observed from THEMIS-A from 23:30 UT to 02:00 UT. The corresponding distributions of the ULF waves in L shell (L) and magnetic local time (MLT) are shown in Figure 2b and 2c. We use a dipole magnetic field model in our study. L in this paper refers to “ L shell”, which is the McIlwain L . The ULF waves are observed in the inner magnetosphere at $L < 5$; we believe that McIlwain L and Roederer L are similar in this range. The time span of Figure 2b and 2c is from 20:00 UT on August 31 to 04:00 UT on September 01. The colors corresponding to each spacecraft are consistent with those in Figure 2a. From Figure 2b we can see that the initially observed poloidal waves covered a wide range of L , from 4 to 8. THEMIS, RBSP, and GOES observations are well separated in MLT, ranging from dawn to afternoon to dusk-night sectors. Figure 2c shows that the waves were located over a wide range of MLT, from 7 to 20.

The schematics of RBSP and MMS during the polarization state variations of the ULF waves in the GSM xy -plane are shown in Figure 2d. The orbit period of RBSP spacecraft is about 9 hours. RBSP-A observed the ULF waves on two consecutive orbits about 9 hours apart: at 06:00–09:35 UT and at 14:50–16:00 UT. RBSP-B observed the ULF waves at 08:00–11:00 UT and 16:50–17:10 UT, also on two consecutive orbits. The orbits of RBSP-A and RBSP-B are very close to each other. MMS observed the ULF waves in a similar location, at 06:20–08:00 UT. The MMS orbit was close to that of RBSP-A during this interval. The spatial distribution of the waves in L and MLT during the polarization state variations is presented in Figures 2e and 2f. The colors corresponding to each spacecraft are consistent with those in Figure 2d. As indicated in Figure 2e, the L shell coverage of the ULF waves from 06:00 to

Figure 1. From the top: (a) *Dst* index; (b) *AE* index; (c) proton number density in solar wind; (d) solar wind speed; (e) solar wind dynamic pressure. Vertical dash lines indicate the intervals of wave observations.

11:00 UT during the first orbit of RBSP is from 4.0 to 7.6. During the second RBSP orbit, the range of L shell coverage became much smaller (4.3–5.5). From Figure 2f, the MLTs of the wave during the first and the second RBSP orbits are ~ 13.4 – 16.5 and ~ 13.4 – 14.6 , respectively. The L and MLT extent of the waves are much smaller than those of the earlier global-scale waves. The ULF waves become more localized in both L and MLT during the polarization state variations. The localization of the ULF waves may significantly affect the resonance interaction with particles (Li et al., 2017).

We examine wave power spectra and waveforms during the periods of polarization state variation. In Figure 3 we present the Fourier dynamic spectra from 20:00 UT on August 31 to 24:00 UT on September 01 of the wave magnetic field from Electric and Magnetic Field Instrument Suite and Integrated Science (EMFISIS) (Kletzing et al., 2013) of RBSP-A and RBSP-B. The 3-D DC electric field data from EFW (Wygant et al., 2013) of RBSP need to be ob-

tained from the $E \cdot B = 0$ assumption and are unavailable for this event. The magnetic field is transformed into a magnetic-field-aligned coordinate system, with a being azimuthally eastward, p being along the 1000s average magnetic field line, and r being radially outward. The dynamic power spectra of the wave fields B_r , B_θ and B_p are analyzed, with a running FFT time window of 20 min. The lag between running FFT time windows is 1 min. ULF wave activities in the Pc4–Pc5 range were detected five times in similar locations by the two RBSP. RBSP-B observed the initial waves for the first time from 23:00–24:00 UT on August 31; the poloidal component was a bit stronger than the toroidal component. ULF waves were again observed by RBSP-A at 06:00–09:35 UT. In the third observation (by RBSP-B at 08:00–11:00 UT), the toroidal component appeared significantly weaker than the poloidal component. During the last two observations (by RBSP-A at 14:50–16:00 UT and by RBSP-B at 16:50–17:00 UT), the wave polarization had become nearly purely poloidal.

Figure 2. Schematics of location of the observed ULF waves in L and MLT. (a)–(c) Observations of ULF waves from 23:00 UT August 31 to 02:30 UT September 01. Red line indicates the orbit of RBSP-B; Pink line indicates the orbit of GOES-13; Green line indicates the orbit of THEMIS-A. (d)–(e) Observations of ULF waves from 01:00 to 19:00 UT September 01. Dark blue and light blue indicate the two orbits of RBSP-A; Pink and Green indicate the two orbits of RBSP-B; the Red line indicates the orbit of MMS-1.

The observations summarized in Figures 2 and 3 demonstrate that the initially poloidal mode is of global scale and was probably generated by fluctuations in the solar wind upstream. The poloidal wave is generally coupled with some toroidal component under the condition of finite m number.

Figure 4 presents the time-varying polarization states in hodogram. Five 10-min intervals of B_a and B_r in the 0.005–0.015 Hz range are analyzed. The spacecraft locations during these intervals were similar. The L shell range was 4.5–5.8; MLT varied from

13.3 to 15. The interval in Figure 4a is the first observation of the initially poloidal waves from RBSP-B (00:10–00:20 UT on September 01). In this interval, the toroidal polarity was strong; $|B_a|/|B_r| \sim 0.82$. Figure 4b is the hodogram of the interval 06:35–06:45 UT from RBSP-A. During this interval, the toroidal mode appears weaker; $|B_a|/|B_r| \sim 0.54$. Two hours later, RBSP-B observed a smaller polarization ($|B_a|/|B_r| \sim 0.39$) of the waves at about the same location. In the last two RBSP orbits in Figure 4d and 4e, RBSP-A observed a polarity with more poloidal components ($|B_a|/|B_r| \sim 0.32$).

Figure 3. Observations of the dynamic power spectra of B_r , B_a , and B_p by RBSP-A and RBSP-B from 23:00 UT August 31 to 24:00 UT September 1.

Following RBSP-A 1.5 hours later, RBSP-B observed a polarity of $|B_a|/|B_r| \sim 0.13$. The hodogram results are consistent with the features described in Figures 2 and 3. A poloidal wave is first observed to be coupled with some toroidal component. Then, as recorded over 18 hours by two RBSP spacecrafts in two consecutive orbits, the ULF waves gradually become purely poloidal.

2.3 Second Harmonic Poloidal Wave With High- m Number

During the variations of polarization state, MMS encounters the poloidal waves on 06:20–08:00 UT September 1 in the out-bounce at $L=4$ –6. We analyze the wave properties from the electric field (Lindqvist et al., 2016) and magnetic field measurements (Russell

et al., 2016; Torbert et al., 2016) observed on MMS-1. Figure 5 presents the filtered waveform of E and B in the 0.005–0.025 Hz band from MMS-1 on 06:30–07:00 UT. B_r , B_a , B_p are plotted in the first panel; E_r and E_a are plotted in the second panel. B_r and E_r are shifted upward 5 nT and 5 mV/m, B_p is shifted downward 5 nT.

The harmonic mode of poloidal oscillations can be identified from the phase difference between B_r and E_a . For even (odd) harmonics, the phase of E_a leads (lags) B_r by 90 degree for a spacecraft located slightly north of the magnetic equator (Singer et al., 1982; Takahashi et al., 2011). The B_r – E_a phase relation is opposite in the southern magnetosphere. It is seen from Figure 5 that the phase of E_a lags B_r by 90 degrees in this event. Combined with the fact

Figure 4. (a)–(e) The hodogram analysis of B_r and B_θ from RBSP-A and RBSP-B during the polarization state variation. Dashed lines are the least squares fits.

that MMS is south of the magnetic equator, the observed wave is an even-number harmonic mode. Considering the value of the eigen-frequency, we conclude that the observed wave is a poloidal standing wave of second harmonic mode.

We use timing from multiple spacecraft measurements of MMS to infer the azimuthal wave number m . Figure 6a show the filtered time series (0.005–0.025 Hz) of B_r and E_θ of MMS-1, MMS-2, and MMS-3 from 06:35 to 06:50 UT. The peak value of the dynamic power spectra is around 0.013 Hz. The four MMS spacecrafts are separated by less than a few 100 km. During this interval MMS-1,

MMS-2, and MMS-3 were close to each other in L . The orbit of MMS-4 was more separated (~ 200 km) from the orbit of other three MMS. Poloidal ULF waves may have spatial structures in terms of the Alfvén resonator that affect the wave profile in the radial direction (Mager and Klimushkin, 2013; Klimushkin, 1998; Klimushkin et al., 2004; Leonovich and Mazur, 1995). The resonator may cause differences in amplitude and phase across different L . Such differences due to radial separation can affect the timing result of the azimuthal wave number m . To achieve a more reliable result for the azimuthal wave number m , we select data from MMS-1, MMS-2, and MMS-3 for the analysis. From Figure 6a, a

Figure 5. MMS1 observations of the ULF poloidal waves. Waveforms of B_r , B_θ , B_ϕ , E_r and E_θ are shown.

clear time lag of B_r (E_θ) can be visually seen between the waveforms from MMS-1, MMS-2, and MMS-3. From the examination of the waveforms, we can estimate qualitatively that the wavelength is of the order of the spacecraft separation (~ 100 km). The timing results from B_r and E_θ are nearly the same. Figure 6b shows the time lags versus the azimuthal separation distances of the spacecraft. The timing between MMS-1–MMS-2, MMS-1–MMS-3, MMS-2–MMS-3 are 10.2 s, 90.4 s and 100.1 s, respectively; the azimuthal separation between MMS-1–MMS-2, MMS-1–MMS-3, MMS-2–MMS-3 are 93.0 km, 162.2 km, 255.4 km, respectively. The azimuthal wavelength from timing is 172 km, corresponding to $m = -232$. We analyze the error estimation of the azimuthal wave number m . The error in the fitted slope of the line is 0.143. The error of m is calculated to be 75 considering that m is inversely proportional to the slope. The second harmonic poloidal wave is of very high m number ($m = -232 \pm 75$) and its propagation is westward.

2.4 Free Energy Source for the High- m Poloidal Waves

The second harmonic poloidal waves lasted for more than 18 hours with time-varying polarization states. We further investigate the free energy for the waves. The analysis for RBSP-A is presented in Figure 7. We use measurement of ion omnidirectional flux spectra from the ECT instrument (Funsten et al., 2013) to

calculate the phase space density f for ions with energy W from 1 keV to 50 keV. There is a close relationship between the differential particle flux K and the particle phase space distribution f ,

$$K = \frac{v^2}{m_p} \cdot f, \quad (1)$$

where K is the differential particle flux, m_p is mass of the measured particle, and v is the particle velocity. Two examples of ion phase space density at 07:50:41 and 15:17:03 UT, respectively, from the two consecutive orbits of RBSP-A are shown in Figures 7a and 7b, in which the bump-on-tail ion distribution function is identified as a positive df/dW gradient. The maximum $W_{\max}$ and minimum $W_{\min}$ energies of the positive gradient region are indicated by dashed lines. The energy for the bump is obtained as $W_{\text{bump}} = (W_{\max} + W_{\min})/2$. The bump energy W_{bump} is 7057 eV in Figure 7a and 9158 eV in Figure 7b.

The bump-on-tail distribution in ring current ions is an important free energy source for the second harmonic poloidal wave (Hughes et al., 1978; Liu W et al., 2013; Takahashi et al., 2018b). And bump-on-tail instability is a very common instability in plasma physics (Fitzenreiter et al., 1984; Berk et al., 1995). Bump-on-tail ion spectra in our study were first reported in Hughes et al. (1978). The bump-on-tail ion spectra correspond to a positive slope ($df/dW|_{\mu, L} > 0$) in the plasma velocity distribution. ULF

Figure 6. (a) Filtered (0.005–0.025 Hz) waveforms of B_r (in blue) and E_a (in red) from MMS-1, MMS-2, and MMS-3. (b) Observed time lags in B_r versus longitudinal separations between MMS satellites.

waves may be excited by a bump-on-tail velocity distribution. ~ 10 keV ions are probably injected into the storm and substorm. The process of particle injection can be from different regions with different energies and different PSD. The large-scale injection may be adiabatic and the small-scale injection may be non-adiabatic. This complexity may lead to a reverse of the plasma energy distribution's slope. In our event, the bump energy of the ions is around 6–12 keV, as shown in Figure 7c and 7d. The phase space density spectrum of protons shows a persistent existence of 6–12 keV ions associated with the waves. The bump-on-tail ions can drive second harmonic poloidal waves through the drift-bounce resonance.

The condition of drift-bounce resonance is $\omega - m\omega_D = N\omega_B$, where ω and m are the wave frequency and azimuthal wave number, respectively, and ω_D and ω_B are the frequencies of particle drift and bounce motion, respectively, and N is the resonance number. ω_B is described as (Roederer and Hones, 1970)

$$\omega_B \approx \frac{\sqrt{\frac{2W}{m_i}}}{4LR_E(1.3 - 0.56 \sin \alpha)}, \quad (2)$$

in a dipole field, where W is particle energy, m_i is the ion mass, and α is the particle's equatorial pitch angle. $N = 0$ is the drift-resonance and $N = \pm 1$ is the drift-bounce resonance. As Southwood (1976) points out, the $N = -1$ particles are more energetic than the $N = 1$ particles. The approximate solutions for the drift-bounce are $\omega \simeq \omega_B$ ($N = +1$) and $m\omega_D \simeq \omega_B$ ($N = -1$). In our event, the free energy is provided by the low energy (~ 10 keV) bounce resonance of $N = +1$. The resonance condition is $\omega \simeq \omega_B$. This scenario is consistent with the westward propagation of the poloidal wave as obtained in the previous section.

More evidence for the $N = 1$ bounce resonance is provided in the last panel of Figures 7c and 7d. We compare the observed eigenmode frequency, the eigen-frequency from the resonance condition $\omega \simeq \omega_B$, and the modeling eigen-frequency expected from the second harmonic poloidal waves. The modeling eigen-frequency for the second harmonic mode is obtained as follows. Cummings et al. (1969) and Orr and Matthew (1971) have shown that the harmonic eigen-frequencies in a dipole magnetic field can be solved numerically. Cummings et al. (1969) uses an idealized model with a background magnetic field of dipole and the plasma density of power law to calculate the eigen-frequency at $6.6R_E$. Orr and Matthew (1971) study the eigen-frequencies for different geocentric distances and provide the relationship between eigen-frequency and L value. Following the approach of Orr and Matthew (1971) and Liu W et al. (2013), we use the modeling relation

$$f_q \propto \frac{1}{\sqrt{n_{eq}L^4}}$$

for second harmonic poloidal waves, where f_q is local eigen-frequency, n_{eq} is the proton density at the magnetic equator, and L is the L -shell value. Using this relation, we plot the modeling eigen-frequency based on the observed plasma density. As shown in the last panel of Figures 7c and 7d, the observed eigenmode frequency (black) matches well with the eigen-frequency of the resonance condition (red) and the modeling eigen-frequency (green) in the presence of the waves. We analyze the average relative errors between observation eigen-frequency, modeling eigen-frequency, and resonance eigen-frequency. The errors between the frequencies for the whole event interval in Figure 7c are 21%, 8%, 14%; in Figure 7d they are 35%, 25%, 10%. We think average relative error under 35% constitutes good agreement and supports the scenario that the ~ 10 keV ions may provide energy to the ei-

Figure 7. (a)–(b) Proton phase space density measured at 07:50:41 and 15:17:03 UT by RBSPA. (c)–(d) Observations of the waves in the first orbit and the second orbit of RBSP-A. Panels from the top are wave power spectra of B_r , proton phase space density, energy of the bump distribution, electron density inferred from RBSP spacecraft potential, and eigenmode frequencies from observed wave (black), from modeling of the second harmonic poloidal wave (green), and from the bounce frequency (red) of protons at the energy of the bump.

genmode through the $N = 1$ bounce resonance. Some difference between modeling and observation may come from uncertainty in the modeling eigenfrequency. The modeling eigenfrequency assumes some specific form of global density distribution. Our observations include measurement of the density only near the equatorial plane, which is not exactly the same as the modeling density. After 09:00–10:00 UT in the first orbit and 16:00 UT in the second orbit, the modeling eigen-frequency of local field lines gradually deviates from the bounce frequency of 10 keV ions. Under this condition, energy can not be transferred from particles to waves. This probably leads to the decrease of the wave activity in these intervals.

Figure 8 analyzes, in format similar to that of Figure 7, the bump-on-tail distributions observed by RBSP-B. The dynamic power

spectra of B_r , ion phase space density, bump energy, electron density, and comparison of eigen-frequencies are shown. RBSP-B detects wave activities three times. The ~ 10 keV bump-on-tail ions are present in all intervals. The errors between the frequencies for the whole event interval in Figure 8a are 13%, 25%, 14%, in Figure 8b are 20%, 25%, 8%, in Figure 8c are 4%, 31%, 30%. Similar to the results of RBSP-A, the observed eigenmode frequency (black) agrees well with the eigen-frequency of the resonance condition (red) and the modeling eigen-frequency (green). In the last orbit on 16:50–17:10 UT of September 1, the decreasing intensity of bump-on-tail ions corresponds to a decrease of wave intensity. Evidence from both RBSP spacecraft supports that ~ 10 keV ions through the $N=1$ drift-bounce resonance contribute to the generation of the poloidal waves.

Figure 8. Observations of RBSP-B in three orbits. Panels from the top are wave power spectra of B_r , proton phase space density, energy of the bump distribution, electron density inferred from RBSP spacecraft potential, and eigenmode frequencies from the observed wave (black), from modeling of the second harmonic poloidal wave (green), and from the bounce frequency (red) of protons at the energy of the bump.

The free energy of the ULF waves may be supplied not only from bump-on-tail plasma distributions, but also from an inward gradient. According to the previous description, the generation of the poloidal wave is related to ~ 10 keV ions. The ~ 10 keV ions work by either bump-on-tail plasma distributions or by inward gradient. We will next study which mechanism provides free energy for the waves. During the particle diffusion along unique paths in W-L space from high density regions to low density regions, wave in-

stability is given by

$$\frac{df}{dW} = \frac{\partial f}{\partial W}|_{\mu,L} + \frac{dL}{dW} \frac{\partial f}{\partial L}|_{\mu,W} > 0, \quad (3)$$

which condition is equivalent to

$$\frac{df}{dL}|_{\mu,J} = \frac{\partial f}{\partial L}|_{\mu,W} + \frac{dW}{dL} \frac{\partial f}{\partial W}|_{\mu,L} < 0 \quad (4)$$

(Southwood et al., 1969) by multiplying both sides by $\frac{dW}{dL}$, where f is the particle distribution function, μ is the first invariant, and J is the second invariant. $\frac{\partial f}{\partial W}|_{\mu,L} > 0$ represents the bump-on-tail distributions while $\frac{df}{dL}|_{\mu,W} < 0$ represents inward gradients distributions. And

$$\frac{dL}{dW} \approx \frac{L^2}{eB_E\omega_d R_E^2}, \quad (5)$$

where e is the elementary charge, B_E is the equatorial magnetic

field magnitude at the surface of the Earth, and

$$\omega_d = \frac{3LW(0.35 + 0.15 \sin \alpha)}{\pi B_E R_E^2}. \quad (6)$$

Figure 9 shows the profile of phase space density (PSD), $\frac{\partial f}{\partial W}|_{\mu,L}$, $\frac{dL}{dW} \cdot \frac{\partial f}{\partial L}|_{\mu,W}$, $\frac{df}{dW}$ fixed at ~ 10 keV ions versus L-shell (L). PA-dependent flux are adopted to calculate PSD here. In general, PSD, f , is defined in the six dimensional phase space, (p, q), where p and q denotes position and momentum respectively. For trapped

Figure 9. From the top: proton phase space density, $\frac{\partial f}{\partial W}|_{\mu,L}$, $\frac{dL}{dW} \cdot \frac{\partial f}{\partial L}|_{\mu,W}$, (a) and (c) are the first and second orbit of RBSP-B, respectively; (b) and (d) are the first and second orbit of RBSP-A, respectively. In the third panel of the four pictures, the black lines represent $\frac{dL}{dW} \cdot \frac{\partial f}{\partial L}|_{\mu,W}$ and the red lines represent $-\frac{dL}{dW} \cdot \frac{\partial f}{\partial L}|_{\mu,W}$. In the fourth panel of the four pictures, the black lines represent $\frac{df}{dW}$, and the red lines represent $-\frac{df}{dW}$.

particles, $f(p, q)$ can be alternatively written as $f(\mu, J, L, \phi_1, \phi_2, \phi_3)$ are action angles corresponding to the periodic motions (Green and Kivelson, 2004). However, our event occurred during storm quiet time and the quiet time was maintained for more than 48 hours before the observation of waves. Hence particles have drifted for tens of hours, much longer than the drift period of keV particles. The system may reach a steady distribution in the ϕ_3 direction, and PSD may be insensitive to ϕ . So we think the dependence on MLT can be neglected. The range of L is from 4.6 to 5.8. Figures 9a and c represent the first and the second observation orbits of RBSP-B while Figures 9b and 9d represent the first and second observation orbits of RBSP-A. To examine whether the waves can gain energy from the protons in drift-bounce resonance, we should check the sign of $\frac{df}{dW}$.

Apparently, $\frac{\partial f}{\partial W}|_{\mu, L}$ was larger than 0 at all times studied, as shown in the second panel of Figures 9a–d. As shown in the first panel of Figures 9a–d, the values of $\frac{\partial f}{\partial L}|_{\mu, W}$ are more often positive than negative. Considering that $\frac{dL}{dW}$ is negative, the values of $\frac{dL}{dW} \cdot \frac{\partial f}{\partial L}|_{\mu, W}$ are more often negative (red) and less often positive (black) in the third panel of Figures 9a–d. Thus, the positive $\frac{\partial f}{\partial W}|_{\mu, L}$ counterbalances the free energy provided by $\frac{\partial f}{\partial W}|_{\mu, L} > 0$. In the first three pictures, the absolute values of $\frac{\partial f}{\partial W}|_{\mu, L}$ are ~ 0.1 –1 while the absolute values of $\frac{dL}{dW} \cdot \frac{\partial f}{\partial L}|_{\mu, W}$ are ~ 0.1 –100. Accordingly, the inward radial gradient is dominant during the first three orbits. In the last picture, the absolute values of $\frac{\partial f}{\partial W}|_{\mu, L}$ are near 0.6 while the absolute values of $\frac{dL}{dW} \cdot \frac{\partial f}{\partial L}|_{\mu, W}$ are between 0.01 and 10. Accordingly, bump-on-tail ions distributions dominate before $L \sim 5.2$ and the inward radial gradient dominates after $L \sim 5.2$. According to the analysis, bump-on-tail ion spectra contribute to the total growth rate $\frac{df}{dL}|_{\mu, J}$. Bump-on-tail ion spectra are directly related to $\frac{\partial f}{\partial W}|_{\mu, L}$ and indirectly contribute to $\frac{\partial f}{\partial L}|_{\mu, W}$ as well. As calculated in Figure 9, bump-on-tail ion distributions produce effects on $\frac{df}{dL}$ through $\frac{\partial f}{\partial W}|_{\mu, L}$ and $\frac{\partial f}{\partial L}|_{\mu, W}$ together.

3. Summary and Discussions

We provide evidence from RBSP, MMS, THEMIS, and GOES that high- m and highly poloidal ULF waves with time-varying polarization states from globally poloidal waves in the magnetosphere are observed. The polarization state variations occur during quiet solar wind and geomagnetic conditions. A global-scale poloidal wave is first observed by multiple spacecraft from 23:00 UT August 31 to 02:00 UT September 01. In the following two consecutive RBSP orbits, the two RBSP spacecraft record the polarization state variations of the waves to highly poloidal waves. The ratio $|B_\theta|/|B_r|$ starts from 0.82, for the initial wave, and decreases to 0.13 as the waves evolve to highly poloidal.

The poloidal waves from polarization variation are much more localized in both L and MLT than the initially poloidal waves. Analysis of MMS measurements shows that the poloidal waves are of second harmonic mode with a high- m number (~ 232). The propagation of the ULF waves is westward. Data from RBSP particle instruments provide evidence that the second harmonic mode poloidal waves are powered by bump-on-tail (~ 10 keV) ion distributions and inward radial gradients through the $N = 1$ bounce resonance. The inward radial gradients are dominant at three of the four orbits. The radial gradient values are sometimes positive and sometimes negative. The negative values provide free energy for wave generation; the positive values counterbalance the free energy provided by $\frac{\partial f}{\partial W}|_{\mu, L} > 0$.

In MHD theory, poloidal Alfvén waves convert to toroidal waves in a finite lifetime due to non-uniform plasmas (Radoski, 1974). The variation of polarization states toward the toroidal waves have been supported by simulations (Mann and Wright, 1995) and observations (Sarris et al., 2009). To our knowledge, our study presents, for the first time, observational evidence of a variation of polarization states toward purely poloidal polarity. Free energy in the energetic ions may be important for understanding this unusual variation of polarization state. The mixed polarity has a finite azimuthal wave electric field which makes it easier to initialize drift-bounce instability. Then, the drift-bounce resonance instability further increases the poloidal component of the ULF waves and supports the variation of polarization state. Although not considered in the MHD theory of Radoski (1974), such kinetic physics may effectively promote variation of polarization states leading to poloidal polarity.

The event in this study may be not uncommon. Many previous studies indicate that kinetic free energy in energetic ions can excite poloidal ULF waves through drift resonance and drift-bounce resonance (Hughes et al., 1978; Oimatsu et al., 2018; Ren J et al., 2017). Non-Maxwellian distributions are common in energetic ions (10–100 keV) in the ring current (Baddeley et al., 2004). Drift-bounce resonance can occur when the bounce frequency of the energetic ions matches the local eigen-frequency of field lines, for instance as in this event. Statistical study from RBSP shows that compressional poloidal waves are distributed evenly over all phases of storms but purely poloidal waves are distributed primarily in the late recovery phase (Dai L et al., 2015). Decay of the ring current might provide free energy for the polarization state variation that leads to purely poloidal waves in the late recovery phase.

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noaa.gov/sem/goes/data/. The OMNI data are available at CDAWeb. The AE and Dst data are provided by the World Data Center for Geomagnetism, Kyoto.

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