

# The existence of saturated vapors in the deep source region of 2017 Pohang earthquake evidenced from seismic tomography

JiaWei Qian<sup>1,2</sup>, HaiJiang Zhang<sup>3\*</sup>, Lei Guo<sup>4</sup>, Uzonna Okenna Anyiam<sup>5</sup>, Changsoo Cho<sup>6</sup>, Kang Hyeun Ji<sup>6</sup>, and HaoRan Ma<sup>2</sup>

<sup>1</sup>School of Carbon Neutrality Science and Engineering, Anhui University of Science and Technology, Hefei 231131, China;

<sup>2</sup>College of Oceanography, Hohai University, Nanjing 210098, China;

<sup>3</sup>Laboratory of Seismology and Physics of Earth's Interior, School of Earth and Space Sciences, University of Science and Technology of China, Hefei 230026, China;

<sup>4</sup>Hebei Earthquake Agency, Shijiazhuang 050022, China;

<sup>5</sup>Geological and Environmental Science, Hope College, Holland, MI 49423, US;

<sup>6</sup>Earthquake Research Center, Korea Institute of Geoscience and Mineral Resources, Daejeon 34132, Korea

## Key Points:

- Three-dimensional velocity images of  $V_p$ ,  $V_s$ , and  $V_p/V_s$  are estimated for the source area of the 2017 Pohang  $M_w5.5$  earthquake.
- Low  $V_p$ , high  $V_s$ , and low  $V_p/V_s$  anomalies are imaged in the deep source area that are related to overpressurized vapors.
- The 2017 Pohang earthquake is initiated around the edge of the low  $V_p/V_s$  area where most of aftershocks are located.

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**Abstract:** Geothermal resources are a promising approach to clean renewable energy; 90% of them are deep reservoirs of hot dry rock that require hydraulic fracturing to create a network of connections among wells to enable efficient heat exchange, known as an Enhanced Geothermal System (EGS). The Pohang EGS project in south Korea led to a devastating  $M_w5.5$  earthquake, triggered by the reservoir's EGS stimulation, the largest earthquake known to have been induced by EGS development. Detailed investigations have been conducted to understand the cause of the Pohang earthquake; the conclusion has been that overpressurized injected fluids migrated into an unknown fault triggering this large earthquake. Detailed velocity images for the source zone of the 2017 Pohang earthquake, which could be helpful for further understanding its inducing mechanism, are unavailable. However, we have assembled detailed aftershock data recorded by 41 local stations installed within about three months after the  $M_w5.5$  Pohang earthquake, and have then applied the  $V_p/V_s$  model's consistency-constrained double-difference seismic tomography method to determine the high-resolution three-dimensional  $V_p$  (compressional wave velocity),  $V_s$  (shear wave velocity), and  $V_p/V_s$  models of the source region that we report here, as well as earthquake locations within the source region. The velocity images reveal that the deep source area of the 2017 Pohang earthquake is dominated by low  $V_p$ , high  $V_s$ , and low  $V_p/V_s$  anomalies, a pattern that can be caused by overpressurized vapors due to high temperatures at these depths. Based on aftershock locations and velocity features, our studies support the conclusion that the 2017 Pohang earthquake was triggered by injected EGS fluids that migrated into a blind fault.

**Keywords:** Pohang earthquake; tomoDDMC; low  $V_p/V_s$ ; saturated vapors; EGS

## 1. Introduction

Potential sources of geothermal energy, which is renewable and sustainable, are widely distributed on the Earth (Lu SM, 2018; Anderson and Rezaie, 2019; Liu HY, 2022). Compared to conventional hydrothermal resources, hot dry rock (HDR) resources at a depth of 3–10 km that contain little or no water account for 90% of

global geothermal resources (Olasolo et al., 2016; Yin XX et al., 2021). To exploit an HDR resource, an Enhanced Geothermal System (EGS) must be constructed to increase the permeability of the reservoir so that fluids can flow between injection and production wells (Yoo et al., 2021). However, EGS development involves hydraulic stimulation that may induce damaging earthquakes such as the moderate  $M2.9$  earthquake at the geothermal site of Soultz-sous-Forêts (Charl ty et al., 2007) the  $M_L3.4$  earthquake at the geothermal site in Basel, Switzerland (H ring et al., 2008), and particularly the large  $M_w5.5$  earthquake in 2017 that occurred near an EGS drilling site in Pohang, Republic of Korea (Kim et al., 2018; Grigoli et al., 2018; Lee et al., 2019).

First author: J. W. Qian, qianjw@hhu.edu.cn

Correspondence to: H. J. Zhang, zhang11@ustc.edu.cn

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In general, three mechanisms have been proposed to explain the induced seismicity due to hydraulic fracturing, including fluid pressure diffusion (Lei XL et al., 2019; Wong et al., 2021), poro-thermoelastic effects (Ellsworth, 2013), and aseismic fault slip (Bhattacharya and Viesca, 2019). Seismicity induced by hydraulic fracturing in EGS projects is more dangerous than in the hydrocarbon industry because fluid injection in crystalline rocks tends to be more seismogenic than in the sedimentary rocks associated with petroleum and natural gas extraction (Evans et al., 2012).

The 2017 Pohang  $M_w$ 5.5 earthquake is so far the largest induced earthquake due to EGS development, and has been studied by various methods (Kim et al., 2018; Grigoli et al., 2018; Ellsworth et al., 2019; Terakawa et al., 2020; Yeo et al., 2020). Geological and geophysical data analyzed by Kim et al. (2018) suggested that the Pohang earthquake was induced by fluids from the EGS site. Grigoli et al. (2018) combined seismological and geodetic analyses to infer that the occurrence of this earthquake was influenced by the injection operations at the nearby EGS site. Ellsworth et al. (2019) comprehensively examined the tectonic stress conditions, local geology, well drilling data, and well stimulation data, and the seismicity induced by injection, and concluded that the 2017 Pohang earthquake was triggered by high-pressure injection into the EGS well that sent fluid into a previously unmapped fault. Choi et al. (2019) provided insights into the source mechanism of the 2017 Pohang earthquake, relating it to reverse reactivations of pre-existing normal faults. Yeo et al. (2020) proposed a multifaceted causal mechanism, using detailed data from the EGS hydraulic stimulation and related on-site seismicity monitoring data. Using aftershock data recorded by a dense regional portable seismic array from 10 November 2017 to 20 October 2018, Kim et al. (2020) applied the double-difference location method (hypoDD) developed by Waldhauser and Ellsworth (2000) to obtain a relative earthquake location of the Pohang earthquake sequence. Terakawa et al. (2020) used focal mechanism tomography to estimate the 3-D pore fluid pressure field in the source region of the 2017 Pohang earthquake.

However, a detailed velocity model of the 2017 Pohang earthquake source region is so far unavailable, and the fluid state causing high pore pressures in the source region is unknown. Accurate information on the 3D velocity structure in the source area is important to understand the seismogenic environment and the mechanism of this and other induced earthquakes. Seismic velocity anomalies in source regions have helped to track fluid migration and thus identify likely inducing mechanisms for earthquakes in shale gas development areas (Tan YY et al., 2020, 2023). Concha et al. (2010) used the double-difference tomography method (tomoDD) to image the  $V_p$  and  $V_s$  of the European HDR geothermal reservoir at Soultz-sous-Forets in order to understand the fluid path. Compared to separate  $V_p$  and  $V_s$  models, the  $V_p/V_s$  model is more sensitivity to fluids and fractures (Christensen, 1996; Takei, 2002). Lin GQ and Wu B (2018) found low  $V_p/V_s$  anomalies in the Geysers Geothermal Field using the simul2000 algorithm; these anomalies suggest the existence of vapors. In this study our goal is to resolve fine velocity structures of the source region of the 2017 Pohang earthquake by applying the  $V_p/V_s$  model's consistency-constrained double-difference seismic tomography method to a significant quantity of aftershock data (Guo H et al., 2018).

This approach is expected to increase significantly the resolution and reliability of the  $V_p/V_s$  model.

## 2. Seismic Data

The Pohang EGS project was intended to develop geothermal energy in a ~4 km deep hot granitic reservoir. Above the granitic reservoir, the strata from deep to shallow in this area are Quaternary sediments, Tertiary volcanic and sedimentary rocks, and Cretaceous volcanic and sedimentary rocks, respectively (Ellsworth et al., 2019). Over the course of approximately four years, from 2012 to 2016, two exploratory wells named PX-1 and PX-2 were drilled into the granitic basement to develop the EGS. PX-1 and PX-2 are six meters apart from each other in the north-south direction on the surface and are about 600 m apart at the bottom (Figure 1b).

Five hydraulic stimulations were conducted between 29 January 2016 and 18 September 2017. The first, third, and fifth stimulations were conducted in PX-2 and the second and fourth in PX-1. The Pohang earthquake occurred approximately two months after the completion of the final stimulation. In total, more than 5800 m<sup>3</sup> of hydraulic fracturing fluid were not recovered after the stimulations (Ellsworth et al., 2019; Terakawa et al., 2020). A volume of fluid this large can play an important role in triggering an induced earthquake, especially via the mechanism of fluid pressure diffusion (Bhattacharya and Viesca, 2019; Terakawa et al., 2020).

For this study, we use seismic phase arrival times of 1124 aftershocks of the 2017 Pohang earthquake, recorded by 41 stations (Figure 1a), collected by the Korea Institute of Geoscience and Mineral Resources (KIGAM). The earthquake magnitudes (Figure 2) were determined by Kim et al. (2020). Seismicity remained at a high level for about three months, but especially during the first 20 days after the mainshock (Figure 2).

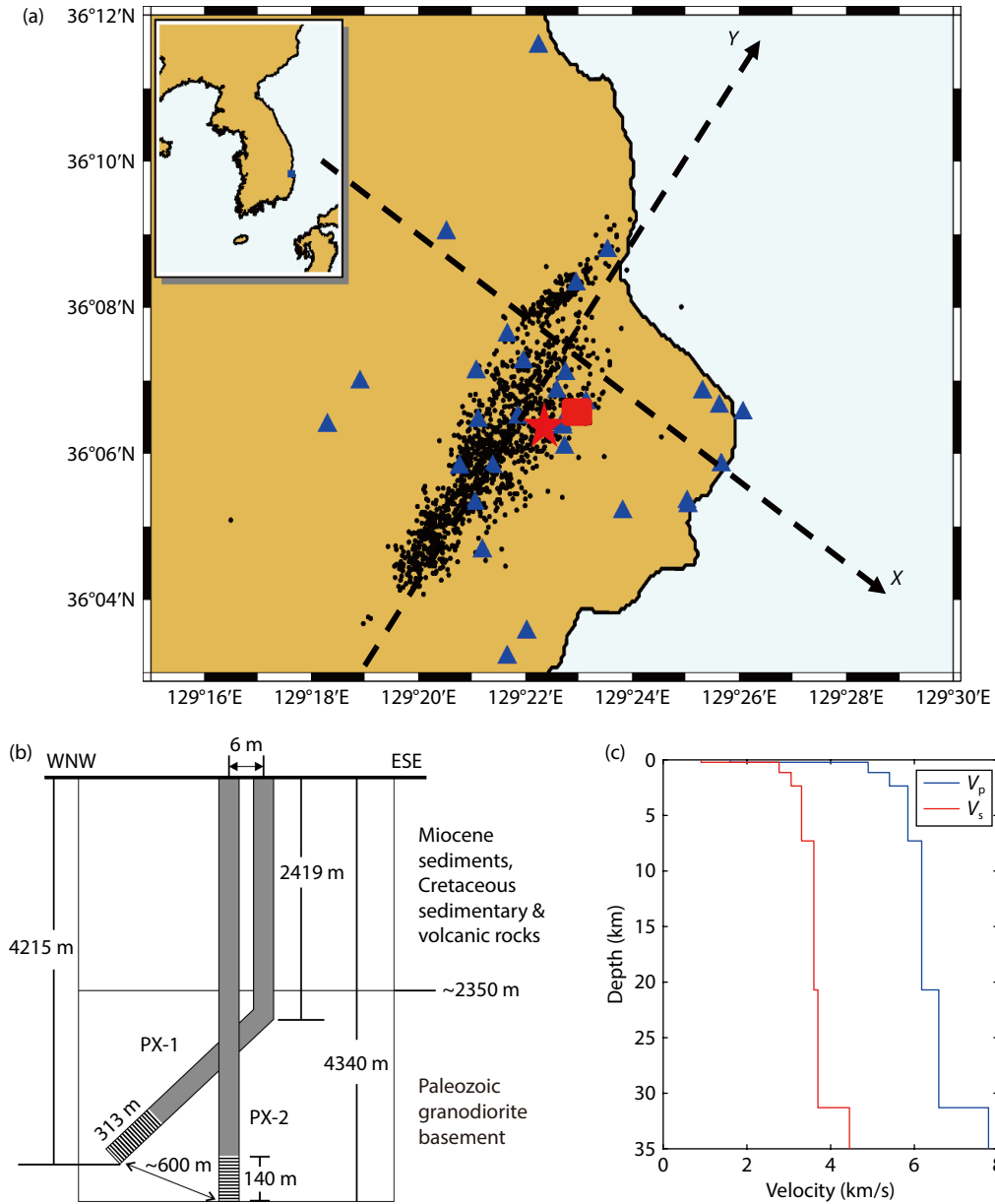
## 3. Seismic Tomographic Method

Zhang HJ and Thurber (2003) developed the original double-difference seismic tomography algorithm (tomoDD) to simultaneously invert velocity structure and event locations. The  $V_p/V_s$  model could be directly derived by dividing  $V_p$  by  $V_s$ . However, because  $V_p$  and  $V_s$  models generally have different model resolutions and uncertainties,  $V_p/V_s$  models obtained simply by dividing  $V_p$  by  $V_s$  inevitably suffer from artifacts (Thurber, 1993; Zhang HJ et al., 2009). In order to obtain a more reliable  $V_p/V_s$  model, Zhang HJ et al. (2009) made use of absolute and differential P, S, and S-P times to jointly invert earthquake locations as well as  $V_p$ ,  $V_s$ , and  $V_p/V_s$  models. On this basis, Guo H et al. (2018) proposed the consistency-constrained double-difference seismic tomography method, creating a more reliable  $V_p/V_s$  model that has a resolution similar to those of the separate  $V_p$  and  $V_s$  models.

Assume that  $k_1$  and  $k_2$  represent the  $V_p/V_s$  model obtained by dividing  $V_p$  by  $V_s$  and by inverting S-P data, respectively. The difference between  $k_1$  and  $k_2$  is defined as

$$\Delta = k_1 - k_2 = \frac{u_s}{u_p} - k_2, \quad (1)$$

where  $u_p$  and  $u_s$  represent the slowness of the P and S waves, respectively. In an ideal case, the difference should be zero; thus



**Figure 1.** (a) Horizontal distribution of the aftershocks (black dots), the seismic stations (blue triangles), the mainshock (red star), and the wells (red square). (b) The schematics of the two exploration wells PX-1 and PX-2 (from Geological Society of Korea). (c) 1-D initial velocity model of  $V_p$  and  $V_s$ .

we can obtain a reliable and high-resolution  $V_p/V_s$  model by minimizing the difference between two  $V_p/V_s$  models, as follows (Guo H et al., 2018):

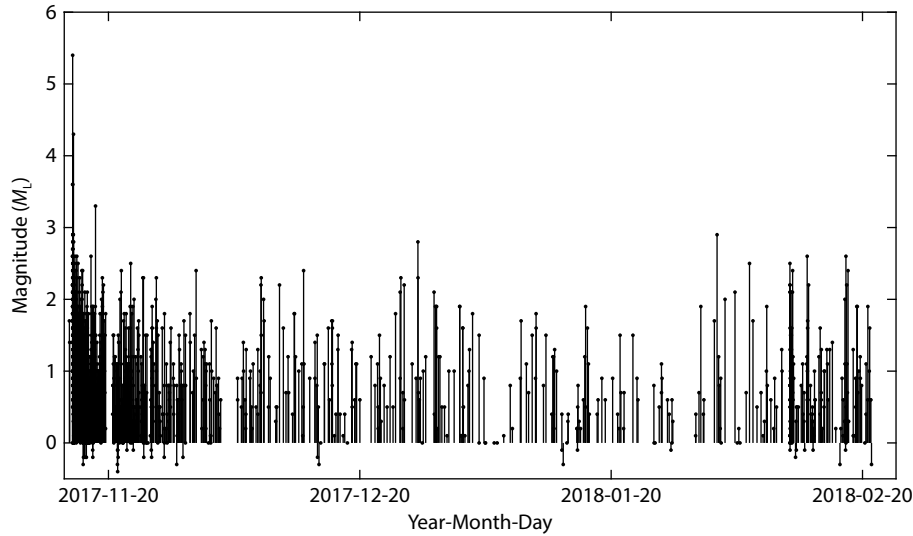
$$\begin{aligned}
 d\Delta &= \Delta^{\text{ture}} - \Delta^{\text{cal}} = k_2 - \frac{u_s}{u_p} \\
 &= \frac{\partial \Delta}{\partial u_p} \delta u_p + \frac{\partial \Delta}{\partial u_s} \delta u_s + \frac{\partial \Delta}{\partial k_2} \delta k_2 \\
 &= -\frac{u_s}{u_p^2} \delta u_p + \frac{1}{u_p} \delta u_s - \delta k_2.
 \end{aligned} \quad (2)$$

The  $V_p/V_s$  model consistency constraint in Equation (2) can be combined with the double-difference seismic tomography system of Zhang HJ et al. (2009) to better determine  $V_p$ ,  $V_s$ , and  $V_p/V_s$  models. This method has been widely used to obtain high-resolution  $V_p/V_s$  models for different regions (Guo H et al., 2018; Zuo KZ

et al., 2020; Anyiam et al., 2023; Cao Y et al., 2023; Tan YY et al., 2023).

#### 4. Tomographic Details and Results

Here we apply the consistency-constrained double-difference seismic tomography method (Guo H et al., 2018) to obtain 3D  $V_p$ ,  $V_s$ , and  $V_p/V_s$  models in the source region of the 2017 Pohang earthquake. Figure 1a shows the Cartesian coordinate system used for the inversion. The location of the EGS site was selected as the coordinate origin. The grid nodes in the depth direction are positioned at  $Z = 0, 0.21, 1.14, 2.35, 3, 4, 5, 6, 7.29, 10, 12, 20.7, 25,$  and  $31.3$  km, respectively. The vertical grid was set referring to local strata. Note that the depth of  $Z = 0$  km represents the depth of mean sea level. Along the  $X$  and  $Y$  directions, the grid intervals are set as 1 km away from the source region and 0.5 km in the



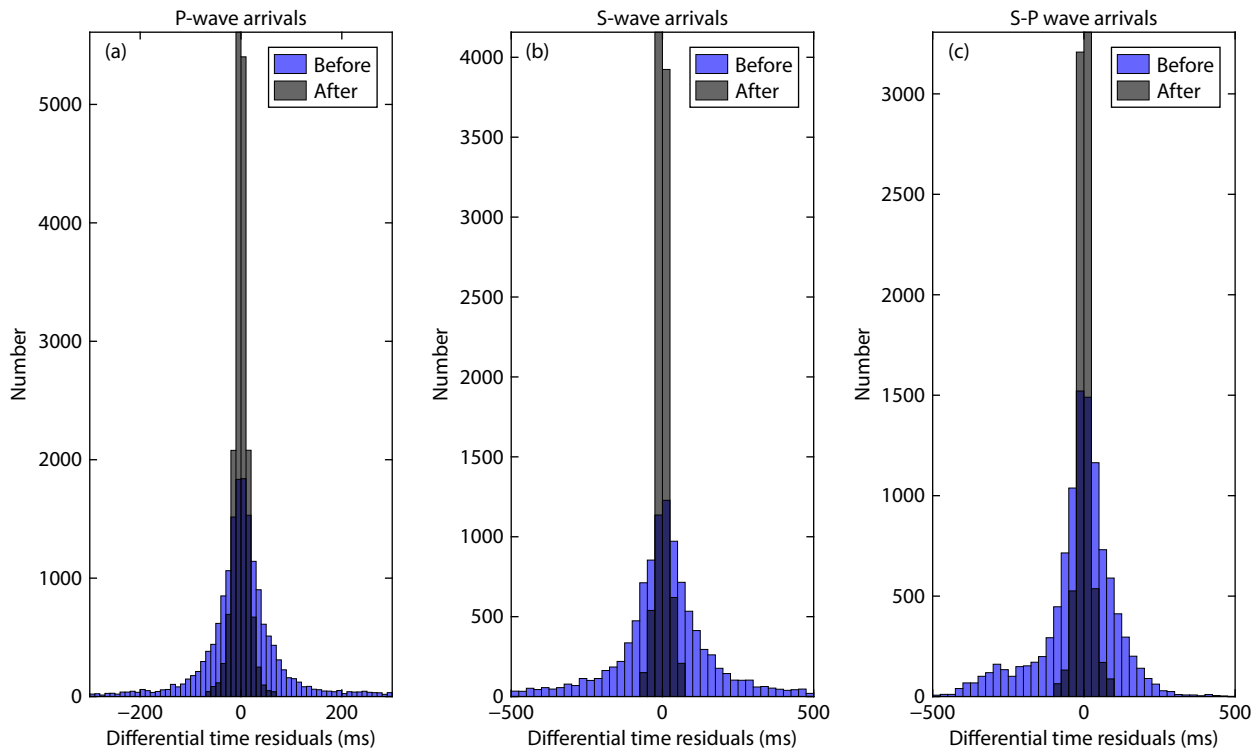
**Figure 2.** Time-magnitude distribution of the Pohang earthquake sequence.

source region. [Figure 1c](#) presents the initial one-dimensional  $V_p$  and  $V_s$  models for the inversion based on the regional velocity model for earthquake monitoring.

For seismic phase arrivals, we assembled 3281 P-wave, 2003 S-wave, and 1377 S-P absolute arrival times, from which differential arrival times can be constructed for event pairs when interevent distances are smaller than 5 km and the number of neighbors is smaller than 8. In total, 29,686 P-wave and S-wave relative arrival times, and 6441 S-P relative arrival times, were constructed. The average offset between event pairs is 0.47 km. After a total of 32 iterations, the root-mean-square (RMS) travel time residual

decreased from 0.060 s to 0.019 s. The travel time residuals after inversion were more concentrated than those before inversion, indicating that the final velocity models better fit the data than the initial model ([Figure 3](#)).

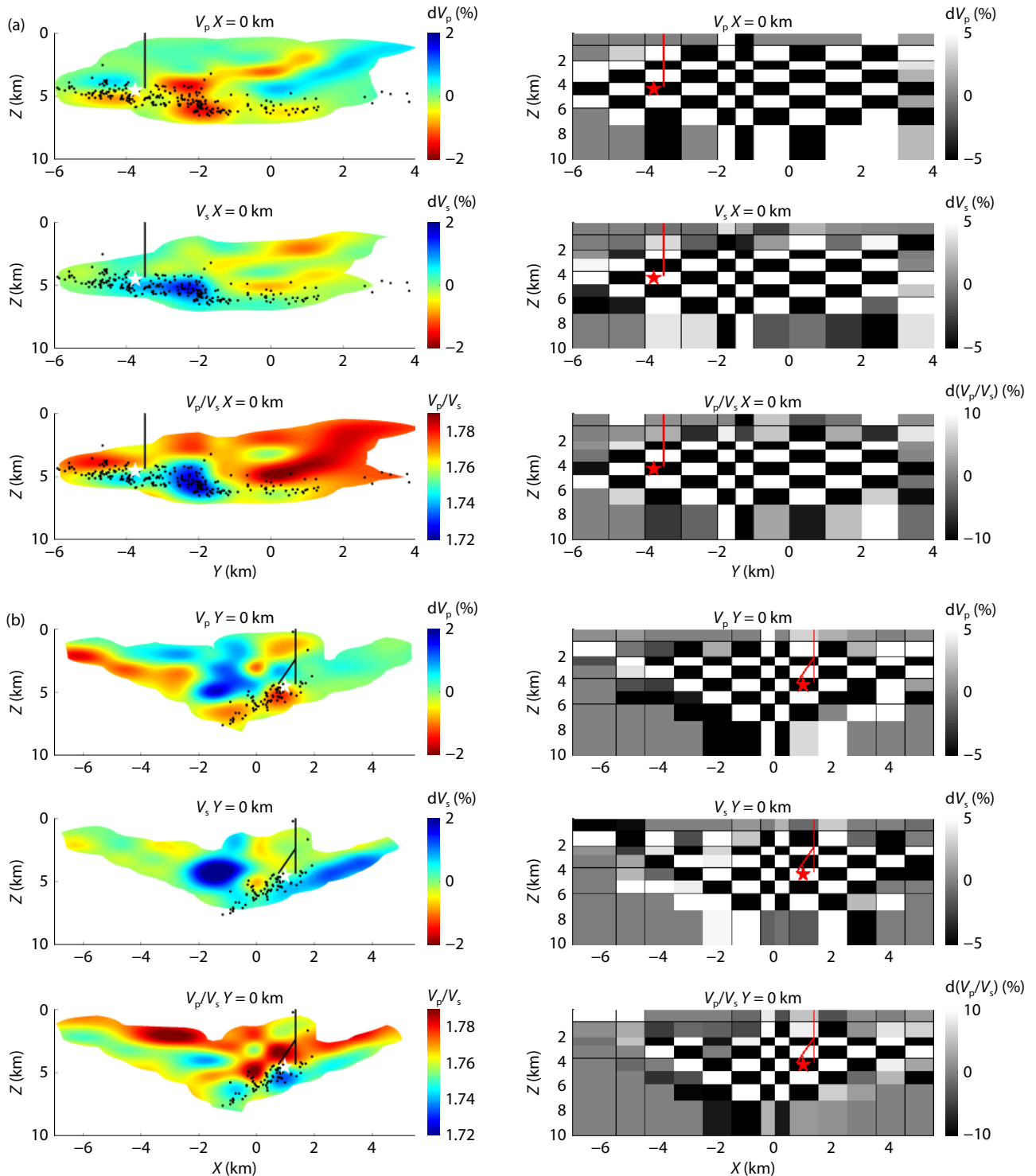
To assess the model's resolution, we performed a checkerboard resolution test similar to previous studies ([Guo H et al., 2018](#); [Zuo KZ et al., 2020](#); [Anyiam et al., 2023](#); [Cao Y et al., 2023](#)). We created synthetic velocity models based on the 1-D initial model with  $\pm 5\%$  perturbations on neighboring grid nodes.  $V_p$  and  $V_s$  perturbations have opposite signs so that the  $V_p/V_s$  model also has checkerboard patterns with anomalies of  $+10.5\%$  and  $-9.5\%$  on adjacent grid



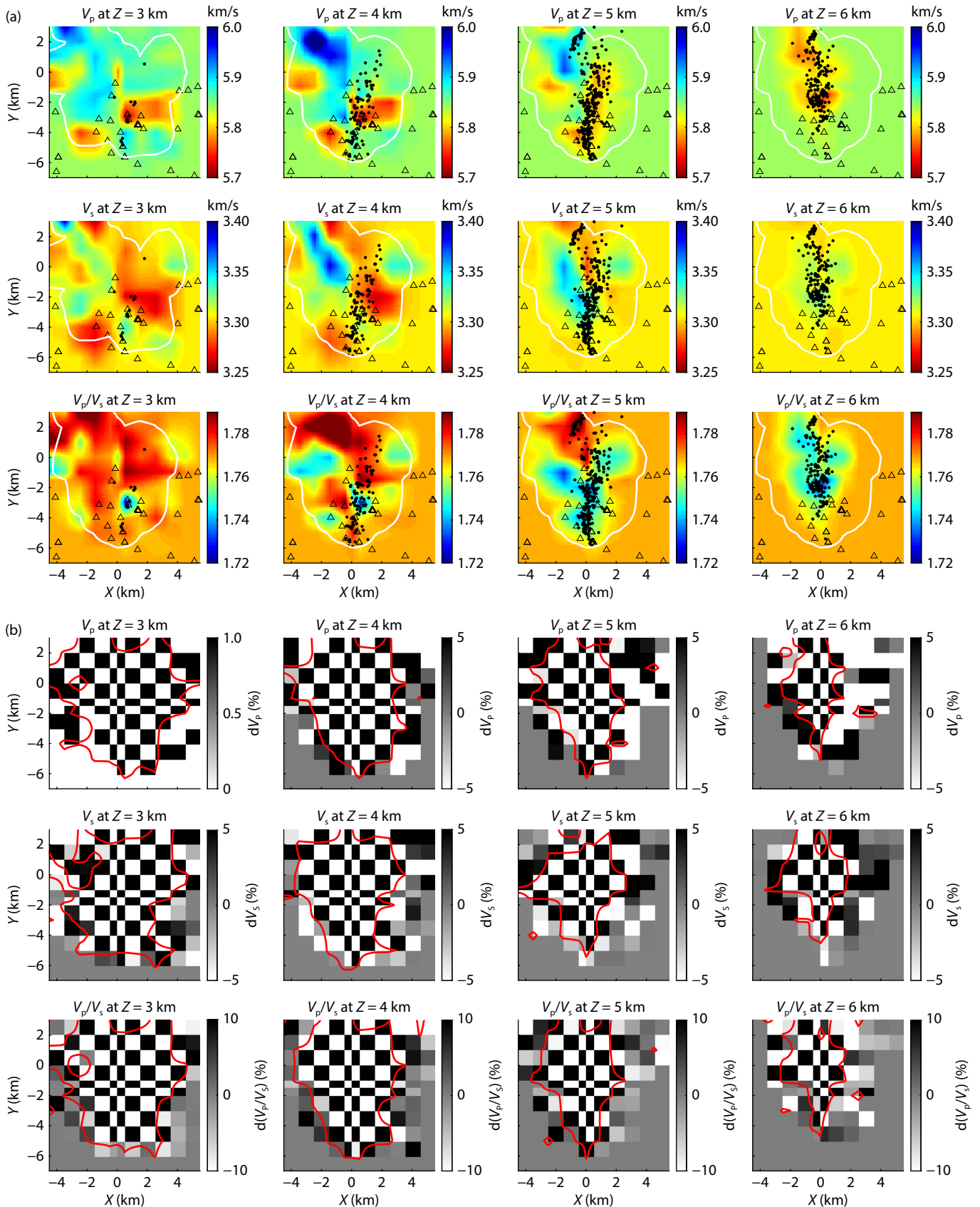
**Figure 3.** Histograms of travel time residuals. Residual histogram after the inversion (grey) is superimposed on residual histogram before the inversion (blue). (a) P-wave arrivals. (b) S-wave arrivals. (c) S-P wave arrivals.

nodes. Based on the synthetic model, theoretical travel times were generated through a pseudo-bending ray-tracing algorithm (Zhang HJ and Thurber, 2003) with the same data distribution as the real data. Finally, the synthetic data were inverted using the same inversion strategy as that of the real inversion.

The two exploratory wells, PX-1 and PX-2, are located near  $X = 0$  km and  $Y = 0$  km, respectively. Figure 4 shows vertical profiles of recovered  $V_p$ ,  $V_s$ , and  $V_p/V_s$  checkerboard models along or across the earthquake clusters at  $X = 0$  km and  $Y = 0$  km, respectively. Figure 5b shows the recovered checkerboard results at depths



**Figure 4.** (a) Cross sections of the P-wave velocity perturbation, S-wave velocity perturbation, and  $V_p/V_s$  structure at  $X = 0$  km and cross sections of the recovered checkerboard models at  $X = 0$  km. (b) Same as (a) but at  $Y = 0$  km. In the left part of (a) and (b), the black lines are the wells, the black dots are the earthquakes, and the white star is the mainshock; only well resolved areas are shown. In the right part of (a) and (b), the red lines are the wells and the red star is the mainshock.



**Figure 5.** (a) Relocated event distribution maps and  $V_p$ ,  $V_s$ , and  $V_p/V_s$  models at different depths. The black dots are the earthquakes projected onto the nearest depth profile. The white lines denote the average DWS values. (b) Recovered results of checkerboard test at different depths. Red contours enclose areas with restoration values greater than 0.85.

from 3 km to 6 km. In order to quantitatively characterize the degree of checkerboard recovery, we adopt a strategy similar to the method proposed by Zelt (1998), where the recovery degree at the  $j$ th grid node can be defined as by (Guo H et al., 2018)

$$R = \frac{(V_{t_j} + V_{r_j})^2}{2(V_{t_j}^2 + V_{r_j}^2)} \quad (3)$$

where  $V_{t_j}$  and  $V_{r_j}$  are the true velocity anomalies and recovered velocity anomalies at the  $j$ th grid node, respectively. Overall, the aftershock area is well-recovered with recovery values greater than 0.85 (Figure 5b), suggesting that the model resolution is high there. This is because the earthquakes are mainly distributed between 3 and 6 km, so the  $V_p$ ,  $V_s$ , and  $V_p/V_s$  checkerboard models are well-recovered in the source region. We also show the well-resolved areas by using the derivative weighted sum (DWS) values. It has been shown that the model regions for which DWS values are greater than the average value are generally well resolved (Zhang H and Thurber, 2007). Figures 4, 5a confirm that model areas with DWS values greater than the average are consistent with the areas of good checkerboard pattern recovery.

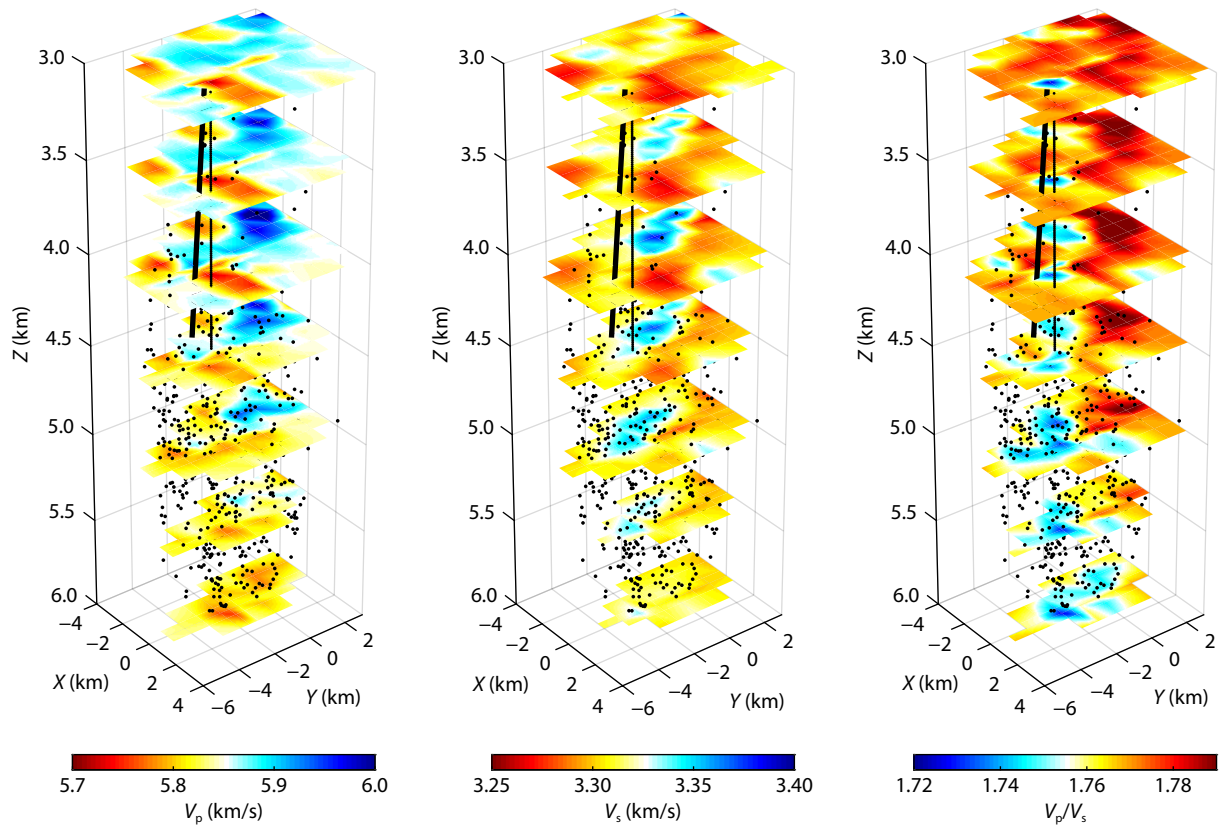
From cross sections of  $V_p$ ,  $V_s$  and  $V_p/V_s$  models at  $X = 0$  km and  $Y = 0$  km, it can be seen that most of the earthquakes are associated with low  $V_p$  ( $\sim 5.76$  km/s), high  $V_s$  ( $\sim 3.34$  km/s), and low  $V_p/V_s$  ( $\sim 1.71$ ) anomalies with respect to background values:  $V_p$  of  $\sim 5.84$  km/s,  $V_s$  of 3.27 km/s, and  $V_p/V_s$  of 1.78 (Figure 4). These features are also clearly observed for depth slices from 5 to 6 km (Figure 5a). In summary, the deep source area of the 2017  $M_w 5.5$

Pohang earthquake is characterized by low  $V_p$ , high  $V_s$ , and low  $V_p/V_s$  anomalies, especially below 4.5 km depth (Figure 6). We also find that, around the depth of 4 km, some aftershocks are associated with relatively low  $V_s$  and high  $V_p/V_s$  values.

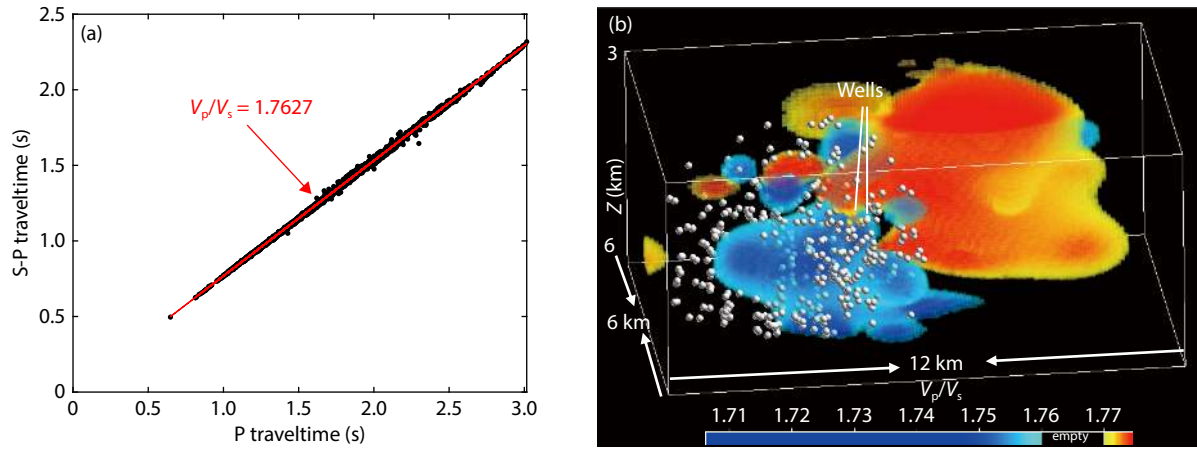
## 5. Discussions

The deep part of the source region below 4.5 km is characterized by relatively low  $V_p$ , high  $V_s$ , and low  $V_p/V_s$  features. For this EGS site, starting from the depth of 2.35 km, the rock type is granite (Kim et al., 2018). The laboratory experiments show that the  $V_p/V_s$  for granite will be increased with pressure and temperature, and can reach 1.75 at the temperature of 100°C and pressure of 350 MPa (Spencer and Nur, 1976). From the Wadati diagram (Wadati and Oki, 1933), the average  $V_p/V_s$  for the region of the EGS site from the source region to the surface is 1.76 (Figure 7a). We further estimate the in situ  $V_p/V_s$  characteristics of the source region using the method of Lin GQ and Shearer (2007); we find that the in situ  $V_p/V_s$  is about 1.7 within the depth range of 4 to 5 km and 1.5 within the depth range of 5 to 6 km (Figure 8). Therefore, the source region where most of aftershocks are located is associated with low  $V_p/V_s$  values (Figures 7b).

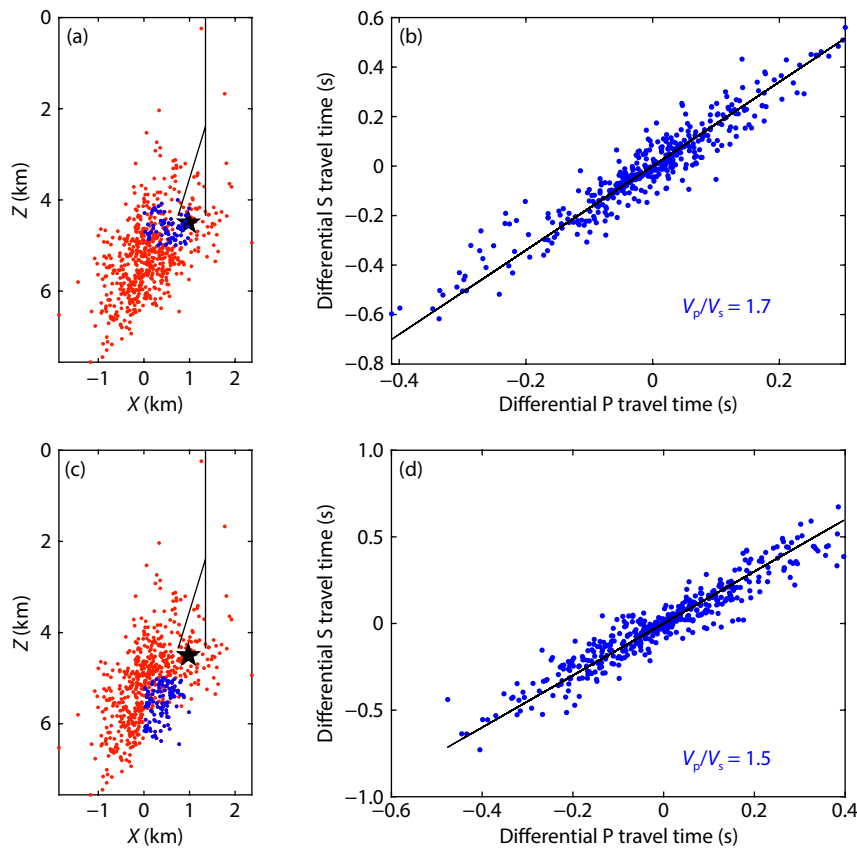
When granite is fractured and saturated with water, the corresponding  $V_p/V_s$  value is generally greater than 1.8 (Wang XQ et al., 2012). However, when fracture aspect ratios are greater (e.g.,  $>0.1$ ), the  $V_p/V_s$  ratio could become lower than 1.7 (Takei, 2000, 2002; Brantut and David, 2019). For example, the earthquake source region in Southern California has median in situ  $V_p/V_s$  of



**Figure 6.** Three-dimensional view of (left)  $V_p$ , (middle)  $V_s$ , and (right)  $V_p/V_s$  models for the depth range of 3 to 6 km. The black lines are the wells and the black dots denote earthquakes.



**Figure 7.** (a) Average  $V_p/V_s$  ratio in the Pohang EGS site via the Wadati method. (b) 3D distribution of relative higher velocity ratios (red,  $>1.77$ ) and lower velocity ratios (blue,  $<1.76$ ) sculpted from the inverted  $V_p/V_s$  model shown in Figure 6. The white dots are the earthquakes.



**Figure 8.** Vertical cross-section view of in-situ  $V_p/V_s$  ratios. The blue dots in (b) and (d) indicate the differential P and S arrival times. The slopes of the lines are the local  $V_p/V_s$  ratio (Lin GQ and Shearer, 2007). In (a) and (c), red dots represent all earthquakes and blue dots represent the earthquakes used for estimating in-situ  $V_p/V_s$  ratios in (b) and (d) respectively.

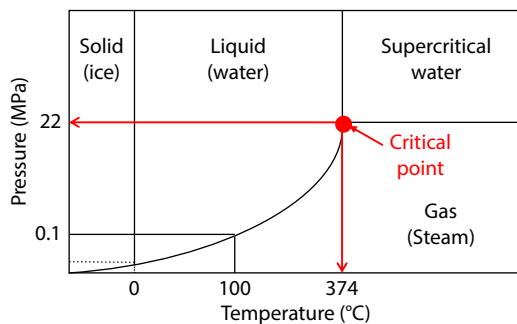
about 1.67 (Lin GQ and Shearer, 2009). However, no matter how the aspect ratios change, fluid-filled cracks generally cause lower  $V_s$  values (Takei, 2000, 2002), which is not consistent with the high  $V_s$  anomalies imaged in the Pohang earthquake source region. Therefore, our observed low  $V_p/V_s$  values in the deep source region of the 2017 Pohang earthquake cannot be explained just by fluid-filled cracks.

Low  $V_p/V_s$  ratios have been observed along the fissure swarm;

they have been interpreted as a product of supercritical fluids (Foulger et al., 1995). Any fluid at a temperature and pressure beyond the critical point is a supercritical fluid. The critical point of water is at 374°C and 22.1 MPa (Sánchez-Pastor et al., 2021). Assessment of geothermal resources in south Korea have found that the temperature at 5 km depth in the Pohang area is expected to be about 180°C (Lee et al., 2010), where the geothermal gradient is  $\sim 30$  °C/km (Lee et al., 2011). Therefore, at the source region, liquids could not reach a critical state because of low

temperatures; thus, our observed low  $V_p/V_s$  anomalies cannot be due to supercritical fluids.

When the temperature is high, as long as the pressure is not very high, the fluids will be in the vapor state (Figure 9). At the depth of 4278 m near the wells, the maximum, intermediate, and minimum principal stresses are 139, 110, and 82 MPa, respectively (Hofmann et al., 2019). In comparison, the maximum recorded wellhead pressure at PX-1 was 27.2 MPa, and the maximum wellhead pressure at PX-2 was 89.2 MPa (Terakawa et al., 2020). Thus in the Pohang earthquake source region, the occurrence of the earthquake is associated with relatively low pressure conditions. Therefore, it is possible that the source region of the 2017 Pohang earthquake was not only filled with overpressurized fluids (Terakawa et al., 2020) but also that these fluids were most likely in a vapor state in the deep area below 4.5 km depth. The lab experiments showed that vapor-dominated pore spaces can increase the S-wave velocity (Toksöz et al., 1976), and decrease  $V_p/V_s$  ratios (Wang XQ et al., 2012). This is consistent with our observations of high  $V_s$  and low  $V_p/V_s$  values. The mechanisms currently proposed to explain how injected fluids can induce earthquakes mainly assume that the fluids are in the liquid state (Schultz et al., 2020). Our tomography results suggest that the vapor state can also play a role in inducing earthquakes and should also be considered.



**Figure 9.** The phase diagram of water (adapted from Sánchez-Pastor et al., 2021).

Around the depth of 4 km, some aftershocks are associated with relatively low  $V_s$  and high  $V_p/V_s$  values. This could be because, at this depth, the fluids have not reached the steam state. Thus, the liquid-dominated cracks cause relatively low  $V_s$  and high  $V_p/V_s$  values. As the depth increases, the temperatures increase, and the injected/leaked fluids start to be in the steam state so that the vapor-dominated cracks lead to the decrease of the  $V_p/V_s$  ratios.

Low  $V_p/V_s$  ratios have also been observed in hydrothermal areas. For example, in the Geysers geothermal field, low  $V_p/V_s$  ratios were observed and interpreted to be caused by a pressure drop of 1 MPa in the steam filled pores from 1991 to 1994 (Julian et al., 1996, Foulger et al., 1997, Gritto and Jarpe, 2014). Similarly, for the source region of the Pohang earthquake, decreased pressure in the vapor-dominated pore spaces in the source area after the main shock rupture could also contribute to low  $V_p/V_s$  ratios observed there.

In this study, in addition to determining the velocity structures of the source area, we also simultaneously determined earthquake

locations, including that of the main shock of the 2017 Pohang earthquake. The RMS travel time residual for the mainshock is 19 ms, indicating it is well relocated. In general, an earthquake's aftershock distribution can be used to delineate the coseismic slip area or the asperity of the mainshock. Previous studies have found that the initiation point of the mainshock is located at the edge of the asperity or the main coseismic slip area (Liu X and Zhao DP, 2018; Li JL et al., 2023). It is also generally accepted that an increase in pore pressures near the asperity (or the strong part along the fault plane) can facilitate initiation of a mainshock. For the Pohang earthquake, we find, as expected, that the mainshock is located around the edge of the aftershock area. Overall, our velocity images further support the hypothesis that the occurrence of the 2017 Pohang earthquake was caused by reactivation of a blind fault due to fluid injections (Choi et al., 2019; Woo et al., 2019).

## 6. Conclusions

In this study, we have created high-resolution 3D  $V_p$ ,  $V_s$  and  $V_p/V_s$  structures for the source area of the 2017 Pohang earthquake by applying a  $V_p/V_s$  model consistency-constrained double-difference seismic tomography method to the earthquake data recorded between 15 November 2017 and 20 February 2018 by a local seismic network. We find that the depth of the mainshock was about 4.5 km, very close to the two exploratory wells. The activated fault, delineated by aftershocks, extends to a depth of 7 km. Aftershocks of the  $M_w$ 5.5 Pohang earthquake were located mainly in a region with relatively high  $V_s$  and low  $V_p/V_s$  values, which can be interpreted as due to overpressured vapors. Our study shows that obtaining detailed velocity structures, especially  $V_p/V_s$  ratios, can help to understand the seismogenic mechanisms of an earthquake. The velocity images presented here support the inference that the 2017 Pohang earthquake was triggered by an increase of pore pressures near its asperity caused by migration of injected fluids into a blind fault.

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